DENSO Robotics　Version Upgrading Information

Notice on Additional and Improved Functions of Controller and Software [Nov 2023]

Thank you for your continued patronage of the DENSO Robotics products.
Please be informed that the following functions will be improved and added in step with upgrading the RC9 Controller and various software versions. We will continue improving our services for our customers, and we wish to ask for your continued patronage.

● Version

RC9	Ver. 1.9.3
WINCAPS III	Ver. 3.66.1

● Item

【 RC9 Controller 】

	Classification	Item
1	Model compatibility	Compatible with Move S command
2	New function	Addition of Asyril EYE+ Provider
3	Performance improved	Added Ver.1.1 inter-compatibility to CC-Link Ver.2.0
4	Name changed	Function name changed from "Master/Slave" to "Mirror Control"

【 WINCAPSⅢ 】

	Classification	Item
1	New function	Added EC9 project comparison function
2	New function	Added path point setting function

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● **Item**

【 RC9 Controller 】

Classification	Item
Compatible with Move S command	RC9 is now compatible with the Move S command. The robot can now be made to operate at a constant speed along a smooth trajectory.
Addition of Asyril EYE+ Provider	An Asyril EYE Provider has been added to simplify interoperation and configuration of cameras and Asycube (a flexible part feeder).
Added Ver.1.1 inter-compatibility to CC-Link Ver.2.0	Made CC-Link Ver.2.0 compatible with Ver.1.1. Communications can now be performed without having to modify programs.
Function name changed From "Master/Slave" to "Mirror Control"	The function name displayed on the teach pendant has been changed from "Master/Slave" to "Mirror Control".

【 WINCAPSⅢ 】

	Item	Outline
1	Added EC9 project comparison function	A project comparison function has been added to the WINCAPS III tools menu. This can be used to compare a project opened in WINCAPS III with a controller project.
2	Added path point setting function	The "path point setting function" has been added. This can be used to register and save position data for multiple path points in a single path data item.